

Reference Specifications

No: 01100028

77 INCREMENTAL

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1. K77 Incremental Optical Encoder (Through shaft)

1.1 Introduction:

K77 is an ultra-thin mechanical flexible connection design, the product is compact, highly integrated, easy to install, and can solve the user's high environmental requirements and installation problems in limited space.

1.2 Feature:

- Encoder external diameter Ø77mm, thickness 31mm, diameter of shaft up to Ø30mm, achieve ultra-thin miniaturization;
- · Ring locking mounting structure;
- Adopt non-contact photoelectric principle;
- · Reverse polarity protection;
- · Short circuit protection;
- · Multiple electrical interfaces available;
- Resolution up to 10000PPR.

1.3 Application:

Motor, CNC and other industrial automation

1.4 Connection:

- · Radial socket (M12 8pin male socket)
- Radial cable (standard length 1M)

1.5 Protection: IP65

1.6 Weight: About 400g

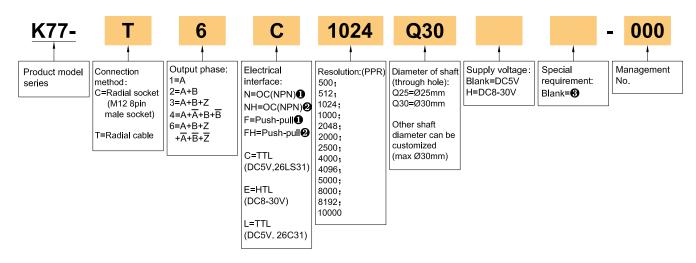


K77-T



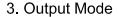
2. Model Selection Guide

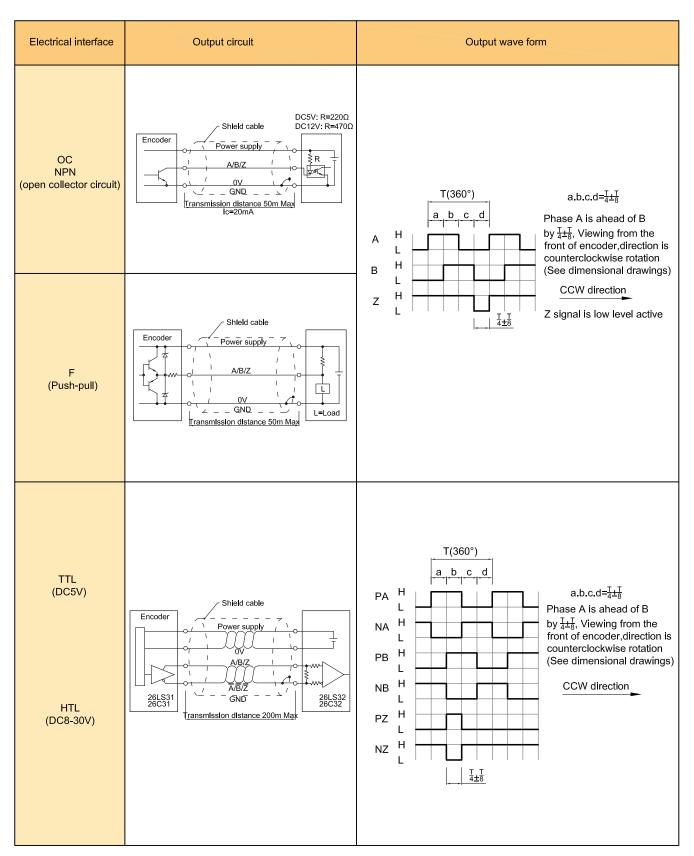
2.1 Model composition(select parameters)



2. 2 Note

- 1. Z signal is low level active.
- 2. Z signal is high level active.
- S. None indicated for IP65 and cable length of 1M, if need to change the length C+number, the longest is 100M (expressed by C100). For the specific length of use, pls refer to page 2 of the provision of output circuit.





4. Electrical Parameters

Parameter Interface			ОС	Push-pull	ΤΤL	HTL	
Supply voltage		ge	DC+5V±5%; DC8V-30V±5%		DC+5V±5%	DC8-30V±5%	
Consumption current)	100mA Max		120mA Max		
Allowable ripple		ple	≤3%rms				
Top response frequency		е	100KHz		200KHz	300KHz	
	Output	Input	≤30mA	≤30mA	≤±20mA	≤±50mA	
acity		Output	_	≤10mA	1 SIZUMA	SISUMA	
Output capacity	Output voltage	"H"	_	≥[(Supply voltage)-2.5V]	≥2.5V	≥Vcc-3 Vpc	
utbut		"L"	≤0.4V	≤0.4V(30mA)	≤0.5V	≤1V VDC	
Ō	Load voltage		≤DC30V	_	_		
Rise	Rise & Fall time		Less than 2us(cable length: 2m)		Less than 1us (Cable length: 2m)	≤100ns	
Insu	Insulation strength		AC500V 60s				
Insulation resistance			10ΜΩ				
Mark to space ratio		ratio	45% to 55%				
Pha	Phase shift		90°±10° (frequency in low speed)				
between A & B		В	90°±20° (frequency in high speed)				
Orig	Origin motion		Low level available —				
GND			not connect to encoder				

5. Mechanical Specifications

Diameter of shaft	Ø25mm; Ø30mm(stainless steel)
Starting torque	Less than 80×10 ⁻³ N·m
Inertia moment	Less than 100×10 ⁻⁶ kg⋅m²
Shaft load	Radial 70N; Axial 50N
Slew speed	≤3000 rpm
Shell material	Aluminium alloy
Weight	about 400g

6. Environmental Specifications

Environmental temperature	Operating: -20~+85°C(repeatable winding cable: -10°C); Storage: -25~+90°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(Endurance)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(Endurance)	1960m/s²,11ms three times for X,Y,Z direction individually
Protection	IP65



7. Wiring table

7.1 Table 1

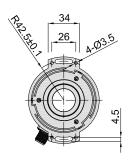
Socket pin definition (M12 8Pin male socket)		Function	Wire color (cable connection)	Explanation
	1	Up	Red	Power supply Positive terminal
	2	Un	Black	Power supply negative terminal
5	3	А	White	A (one turn pulse signal)
6 0 04	4	-	-	Unallocated
70 03	5	В	Green	B (one turn pulse signal)
	6	-	-	Unallocated
	7	Z	Yellow	Z(zero signal)
	8	-	-	Unallocated
	GND	GND	GND	No encoder body connected

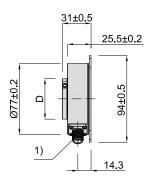
7.2 Table 2

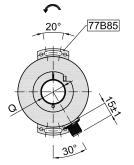
Socket pin definition (M12 8Pin male socket)		Function	Wire color (cable connection,Twisted pair)		Explanation
	1	Up	Red	7000	Power supply
	2	Un	Black		т ожог оцрргу
5	3	А	White	7000	А
6 0 04	4	Ā	White/BK		(one turn pulse signal)
70 03	5	В	Green		В
	6	B	Green/BK		(one turn pulse signal)
	7	Z	Yellow		Z(zero signal)
	8	Z	Yellow/BK		2(2515 Signal)
	GND	GND	GND	GND	No encoder body connected

8. Basic Dimensions

8.1 K77-C(Radial socket connection)





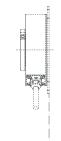


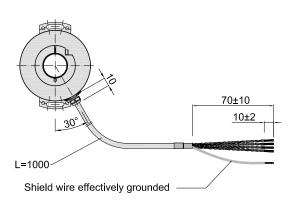
Q(diameter of shaft)	D
Ø25 ^{G7} (^{+0.028} _{+0.007})	Ø44
Ø30 ^{G7} (^{+0.028} _{+0.007})	Ø46

This side is the front of the encoder

8.2 K77-T(Radial cable connection)



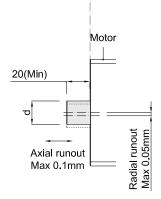


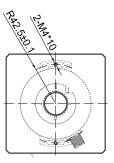


9. Assembly Requirements



Mounting screws Inner hexagon bolt +flat washer Specification: M4*10 Material: stainless steel Quantity: 2





Unit: mm



= Shaft rotation direction of the signal output

1) = M12 8Pin male socket

About vibration

Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.

10. Recommended Accessories

Plug and cable	Brief description	No.	Order No.
	C2C=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 2M 8-core with shield,halogen-free PUR	K77C2C	44400001
	C5C=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 5M 8-core with shield,halogen-free PUR	K77C5C	44400002
	C1=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 1M 8-core with shield,halogen-free PUR	K77C1	44400003
	C2=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 2M 8-core with shield,halogen-free PUR	K77C2	44400004
	C5=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 5M 8-core with shield,halogen-free PUR	K77C5	44400005

